Appl. No. 10/803,889 Amdt. Dated 04/12/2006 Reply to Office Action of 01/12/2006

Amendments to the Specification:

Please replace the below-identified presently pending paragraphs in the patent application with the replacement paragraphs provided.

Paragraph beginning on page 3, line 4:

In the configuration shown in Figs. 3 and 4, the rotation of the serve servo motor 59 for nozzle touch is transmitted to the driven pulleys 58A and 58B through the driving pulley 60 and the timing belt 61, so that the nut pieces 57A and 57B rotating together with the driven pulleys 58A and 58B rotate relatively to the ball screw shaft portions 56A-1 and 56B-1 respectively. Thus, the nut pieces 57A and 57B move linearly along the ball screw shaft portions 56A-1 and 56B-1 respectively so that the heating cylinder retention member 53 and hence the two injection units move linearly together with the nut pieces 57A and 57B.

Paragraph beginning on page 8, line 25:

In the configuration shown in Figs. 1 and 2, the two serve servo motors 9A and 9B for nozzle touch are rotated synchronously. The rotation of the servo motor 9A is transmitted to the driven pulley 8A through the driving pulley 10A and the timing belt 11A, so that the nut piece 7A rotating together with the driven pulley 8A rotates relatively to the ball screw shaft portion 6A-1. Thus, the nut piece 7A moves linearly along the ball screw shaft portion 6A-1. On the other hand, the rotation of the servo motor 9B is transmitted to the driven pulley 8B through the driving pulley 10B and the timing belt 11B, so that the nut piece 7B rotating together with the driven pulley 8B rotates relatively to the ball screw shaft portion 6B-1. Thus, the nut piece 7B moves linearly along the ball screw shaft portion 6B-1. As a result, the heating cylinder retention member 3 and hence the two injection units move linearly together with the nut pieces 7A and 7B.

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